



# Vehicle Signal Manager [VSM]

May 11, 2017 | Project Overview

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**Rudolf J Streif**

*Expert Group Lead, GENIVI Alliance*

**Which feature gets the  
"Volume Up" button press?**

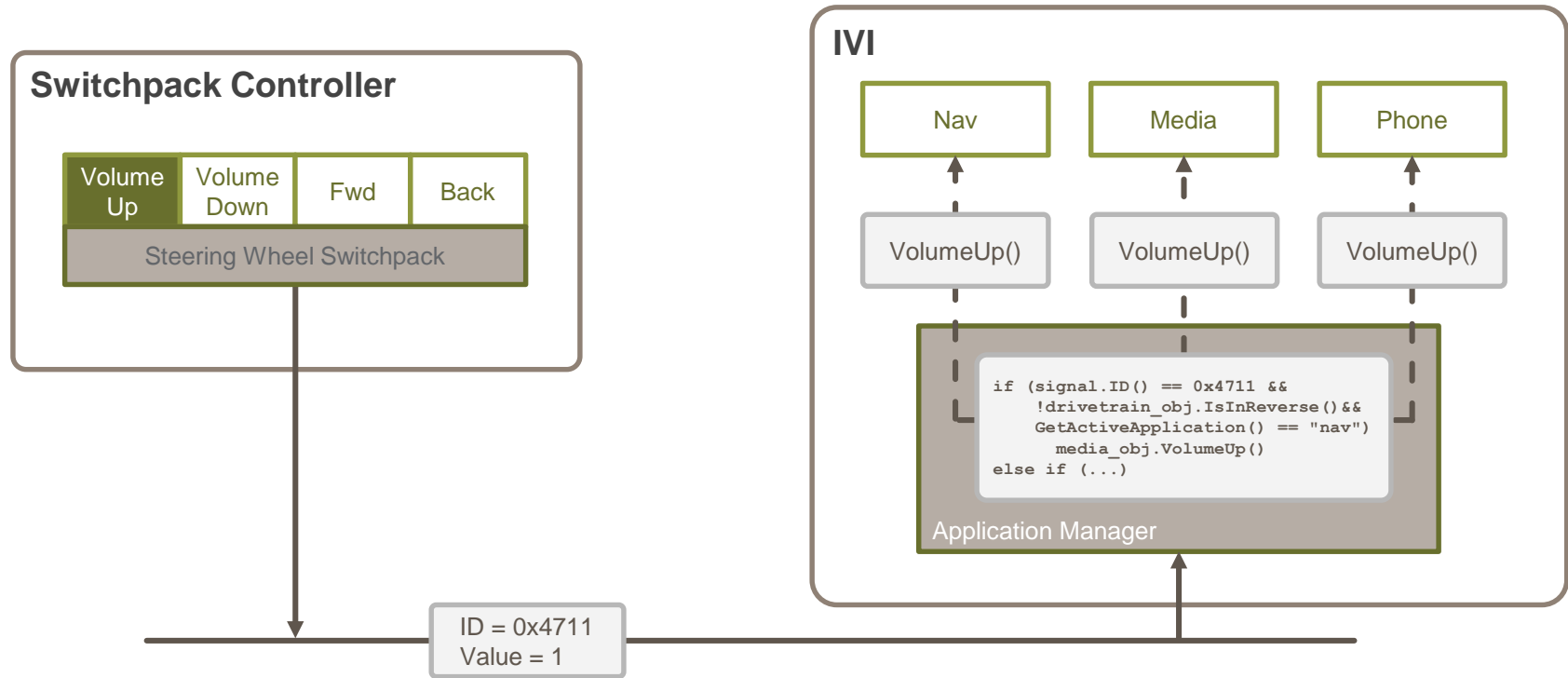


# Vehicle state dictates use cases

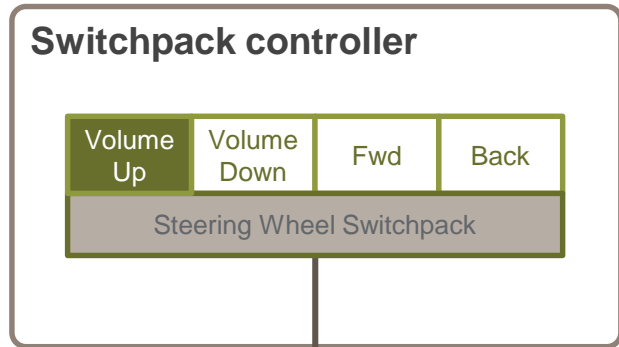
"Volume Up" pressed:

- **Are we in reverse?**  
Increase Parking Assist volume.
- **Is Navigation active**  
Increase Nav Volume.
- **Are we in an ongoing phone call?**  
Increase Phone Volume.
- **None of the above?**  
Increase Media Volume.

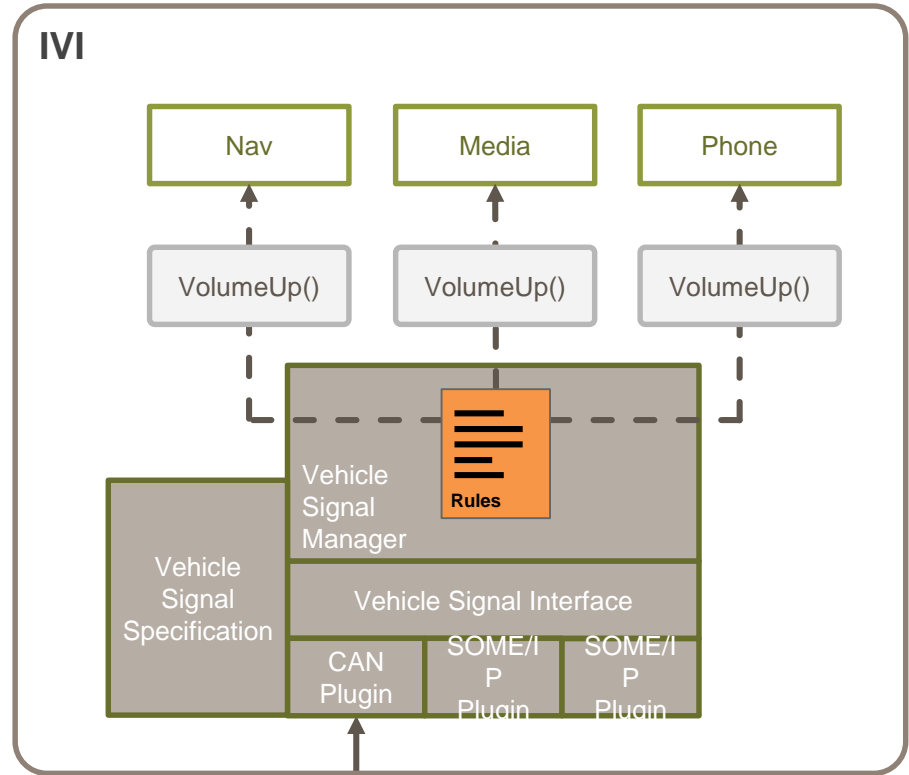
# We need to move signal logic out of the code...



# ... into rule files



ID = 0x4711  
Value = 1



# Benefits

- **Manage variance complexity**

One system to handle use cases across vehicle lines, configuration, and regional legislation.

- **Provides testing framework**

The rule specification driving the signal distribution can also be used to validate signal sequences and timing during test.

- **Updateable via OTA**

Updated rule specifications can be pushed over the air, without the complexities of SOTA, to adjust fleet behavior.

# Project Goals and Objectives

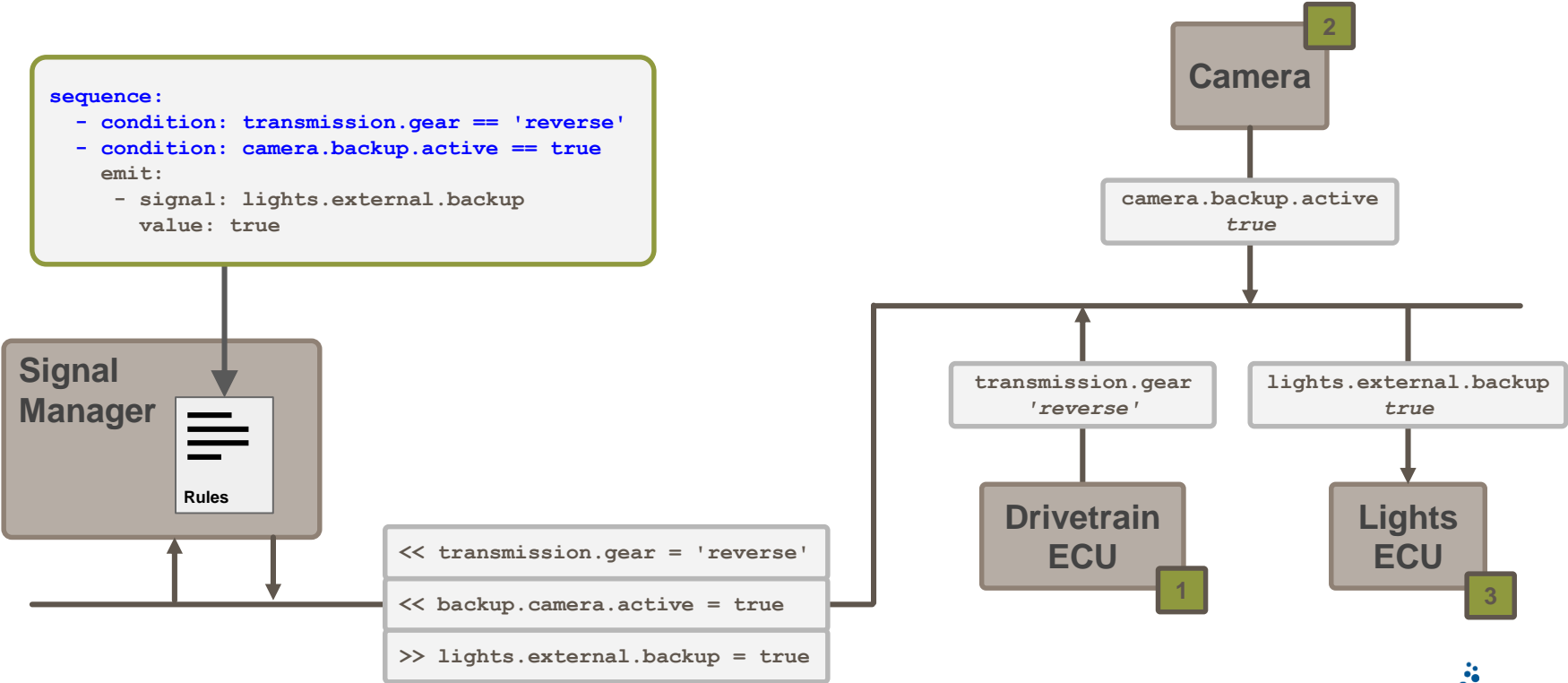
- **Explore signal transformation space**  
Can signal transformation be used to extract call flow logic from features?
- **Understand boundaries between state machines and features**  
What do we encode in signal manager and what stays in the feature?
- **Prepare for production-level implementation**  
Lessons learned fed into potential production variant of the manager.

# What is a VSM rule?

- **Monitors vehicle signals for specific conditions ...**
  - `condition: transmission.gear == 'reverse'`
- **... and then emits signals or makes API-calls on its own**
  - `emit:`
    - `signal: lights.external.backup`
    - `value: true`
- **All encoded as YAML**

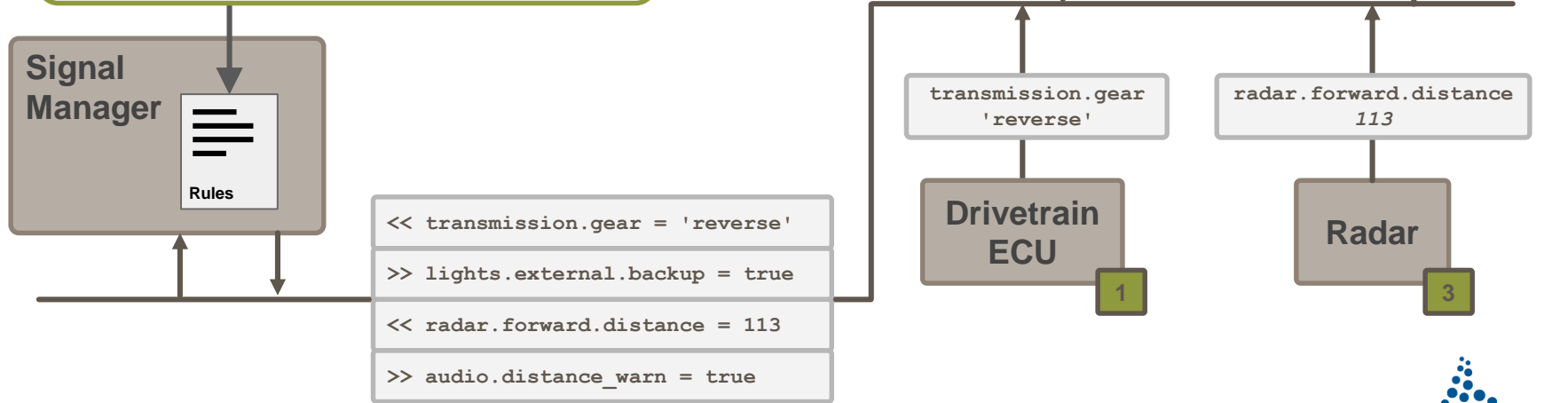


# Conditions can be monitored in sequence ...

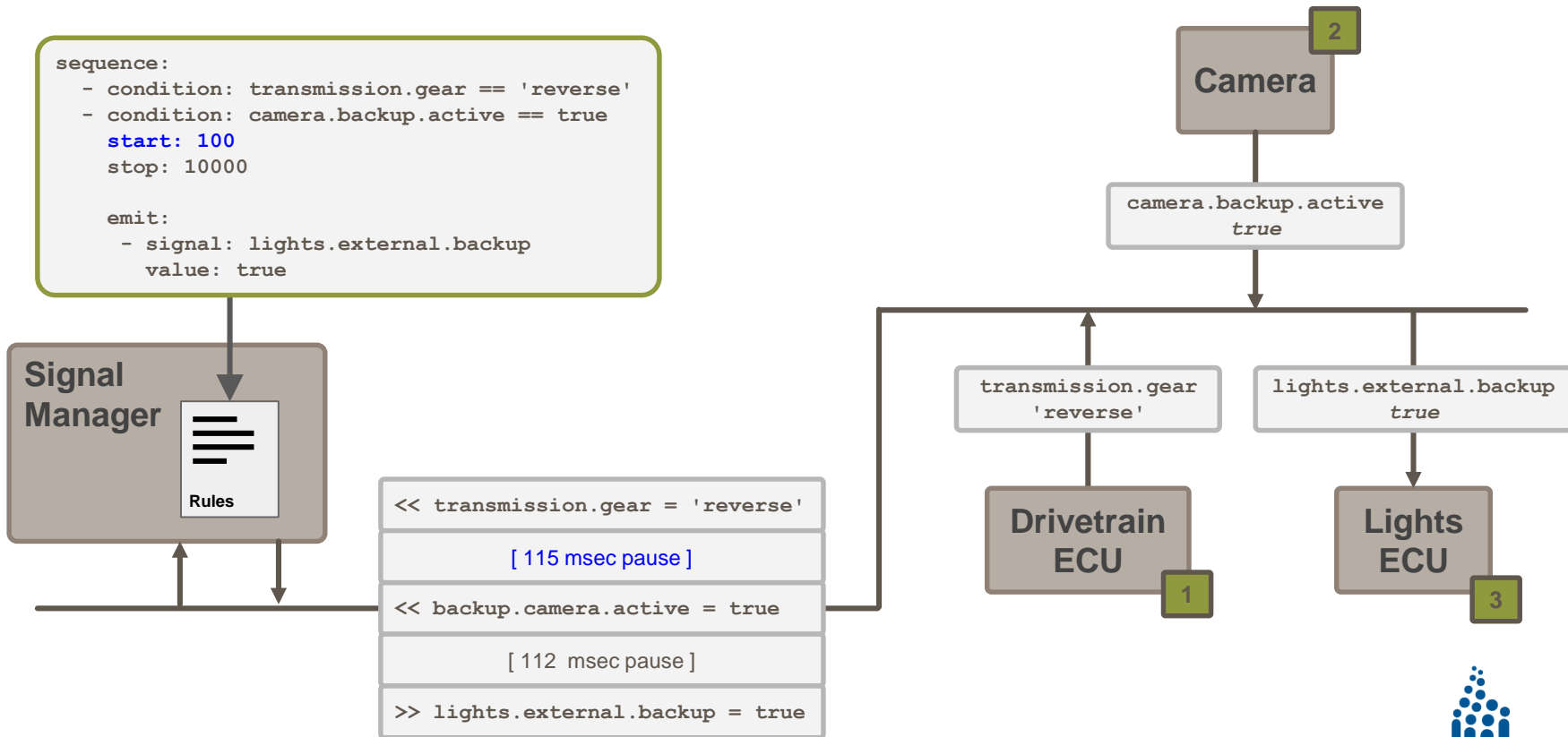


# ... Or in parallel

```
parallel:  
- condition: transmission.gear == 'reverse'  
  - emit:  
    signal: lights.external.backup  
    value: true  
  
- condition: radar.forward.distance < 120  
  - emit:  
    signal: audio.distance_warn  
    value: true
```



# Add timing to get a test specification



# Conditions can be nested...

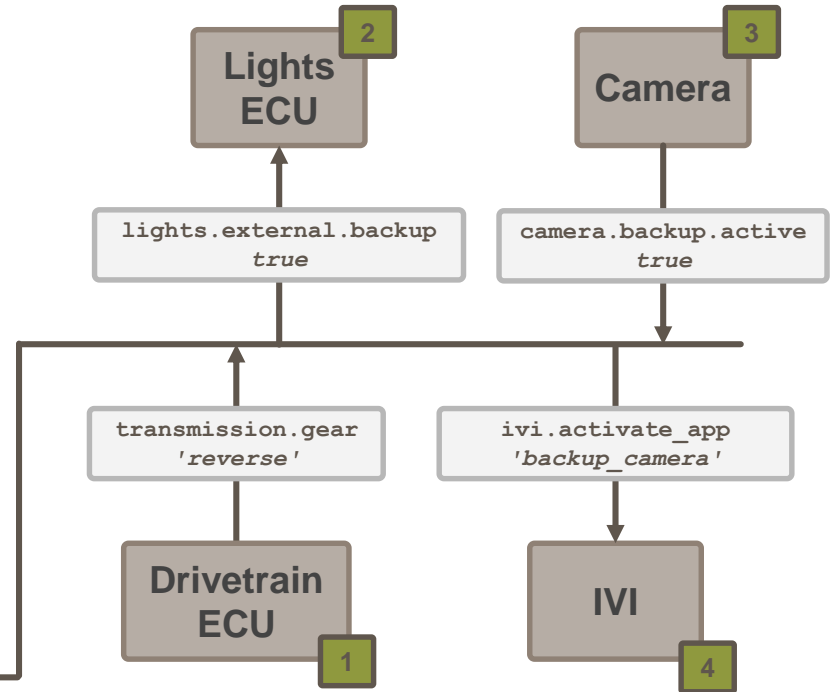
```
# Wait for gear to go into reverse
- condition: transmission.gear == 'reverse'
  - emit: # Turn on backup lights
    - signal: lights.external.backup
      value: true

# After lights turned on, wait for backup camera
- condition: camera.backup.active == true
  - emit: # Activate backup camera app
    - signal: ivi.activate_app
      value: 'backup_camera'

# Monitored in parallel with transmission.gear
- condition: ...
```



```
<< transmission.gear = 'reverse'
>> lights.external.backup = true
<< camera.backup.active = true
>> ivi.active_app = 'backup_camera'
```

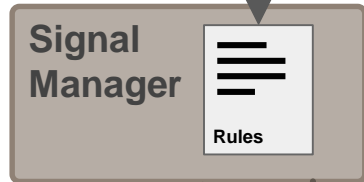


# ... and cancelled if parent condition turns false

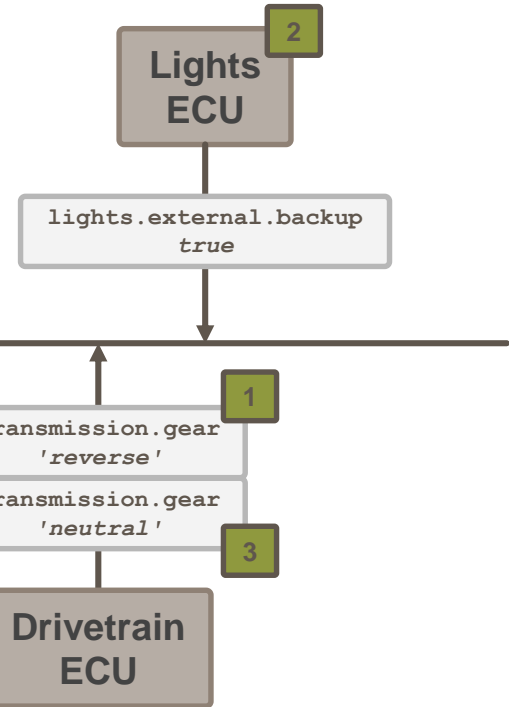
```
# Wait for gear to go into reverse
- condition: transmission.gear == 'reverse'
  - emit: # Turn on backup lights
    - signal: lights.external.backup
      value: true

# After lights turned on, wait for backup camera
- condition: camera.backup.active == true
  - emit: # Activate backup camera app
    - signal: ivi.activate_app
      value: 'backup_camera_app'

# Monitored in parallel with transmission.gear
- condition: ...
```



```
<< transmission.gear = 'reverse'
>> lights.external.backup = true
<< transmission.gear = 'neutral'
```

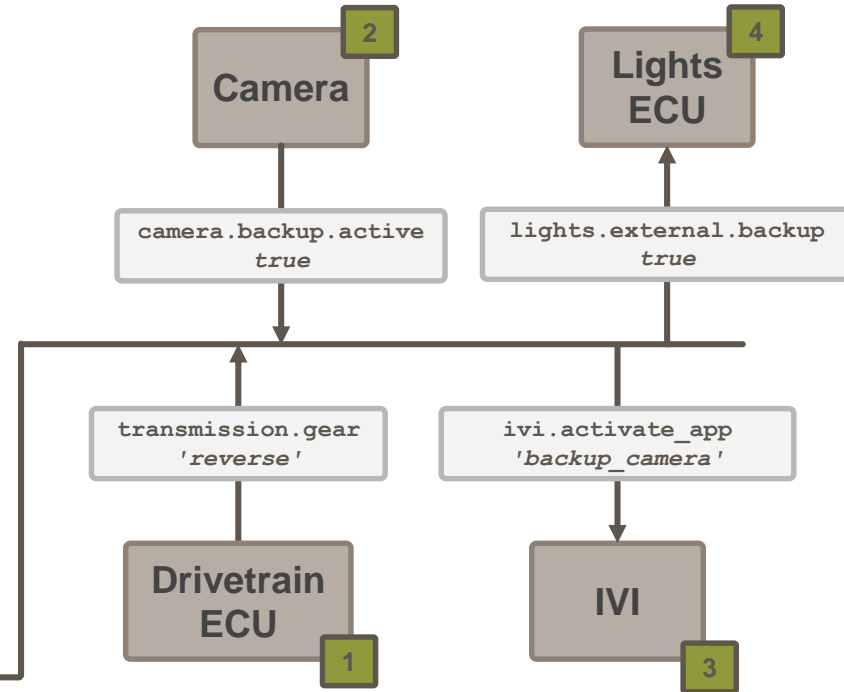


# Conditions can be arbitrary expressions...

```
# Wait for gear to go into reverse and backup camera  
# to be active before turning on backup lights and  
# activate infotainment.  
- condition: transmission.gear == 'reverse' &&  
             camera.backup.active == true  
  
- emit: # Turn on backup camera and backup lights  
  - signal: ivi.activate_app  
    value: 'backup_camera'  
  - signal: lights.external.backup  
    value: true
```



```
<< transmission.gear = 'reverse'  
<< camera.backup.active = true  
>> ivi.active_app = 'backup_camera'  
>> lights.external.backup = true
```



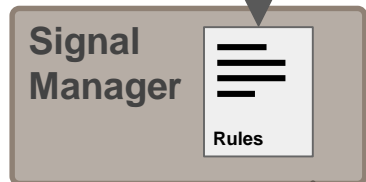
# ... that can include signal values

```
# $-denoted signals are substituted for their values
```

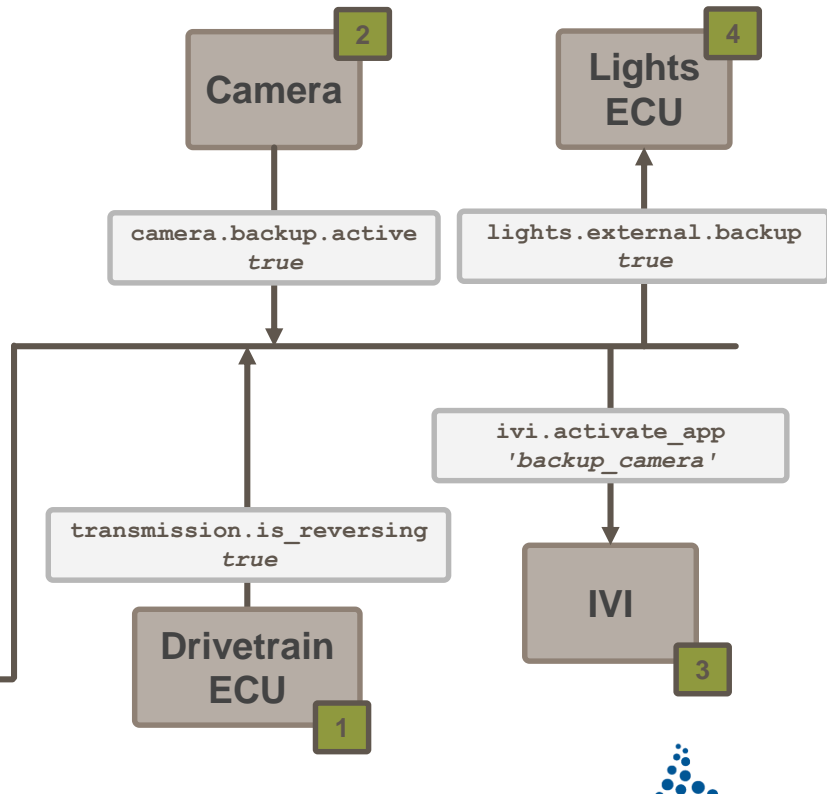
```
- condition: transmission.is_reversing == true &&  
            camera.backup.active ==  
            $transmission.is_reversing
```

```
- emit: # Turn on backup camera and backup lights
```

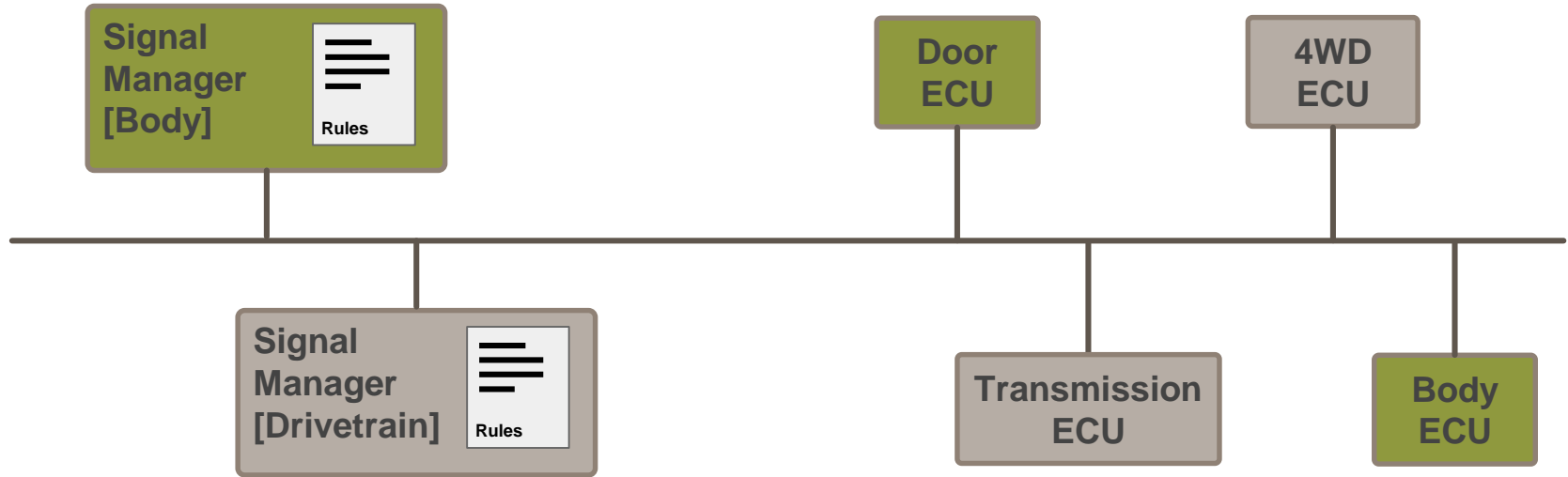
```
- signal: ivi.activate_app  
  value: 'backup_camera'  
- signal: lights.external.backup  
  value: $transmission.is_reversing
```



```
<< transmission.is_reversing = true  
<< camera.backup.active = true  
>> ivi.active_app = 'backup_camera'  
>> lights.external.backup = true
```

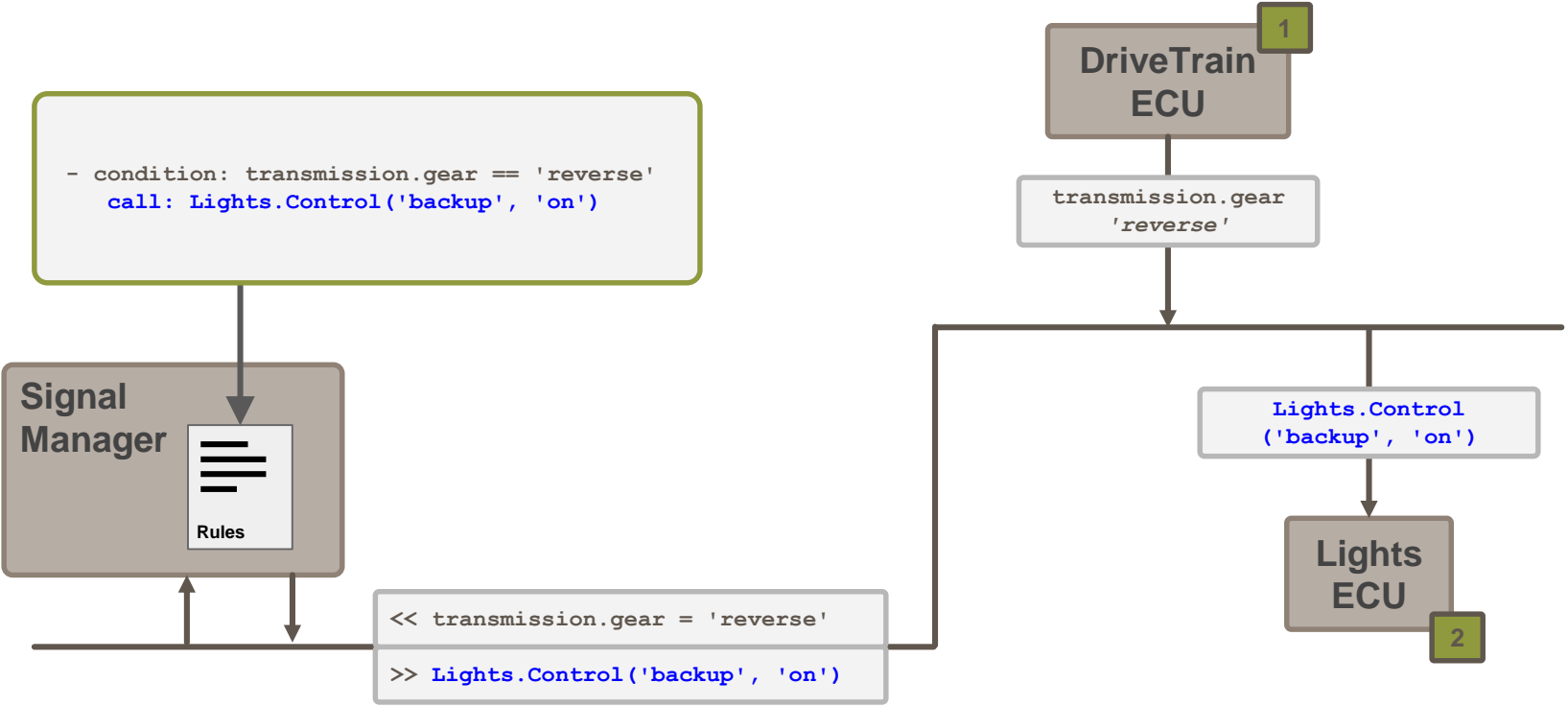


# You can run multiple signal managers in parallel





# Future: API calls?



# Conclusion

- **Separate out call flow logic to manage variance complexity**  
Separate rule YAML files for different models, markets, and configuration.
- **Rules are testable in the rig and in the field**  
Timing information can be left in production to detect issues in deployed fleet.
- **Simplified OTA**  
Rules can be pushed over the air without the full validation and installation process required by a software update.

# Thank you!

Rudi Streif, Jaguar Land Rover - [rstreif@jaguarlandrover.com](mailto:rstreif@jaguarlandrover.com)  
Magnus Feuer, Jaguar Land Rover - [mfeuer1@jaguarlandrover.com](mailto:mfeuer1@jaguarlandrover.com)

Project: [https://github.com/genivi/vehicle\\_signal\\_manager](https://github.com/genivi/vehicle_signal_manager)  
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